

# Mellon M. Zhang

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 Mellon (Meilong) Zhang |  meilongzhang |  Mellon M. Zhang |  meilongzhang

Atlanta, Georgia - Citizenship: US

## RESEARCH INTERESTS

My research aims to improve the reliability and trustworthiness of perception-based robotic algorithms and foundation models in safety-critical and dynamic scenarios. I am particularly interested in multimodal and spatiotemporal reasoning, vision-language-action models (VLAs), and video understanding (Vid-LLMs).

## EDUCATION

- **Georgia Institute of Technology** Aug 2023 - Current  
*Ph.D. in Machine Learning, advised by Prof. Glen Chou* Atlanta, USA
- **University of California, Berkeley** Aug 2019 - May 2023  
*B.A. in Computer Science* Berkeley, USA

## PAPERS

C=CONFERENCE, W=WORKSHOP, S=IN SUBMISSION, P=IN PREPARATION

- [S.2] M. M. Zhang, G. Chou, and S. Mukhopadhyay. **Polar Hierarchical Mamba: Streaming LiDAR Object Detection with Point Clouds as Egocentric Sequences**, 2025. *Under review.* [\[pdf\]](#)
- [W.1] M. M. Zhang and G. Chou. **Towards Streaming LiDAR Object Detection with Point Clouds as Egocentric Sequences**, 2025. *Workshop on 4D Vision: Modeling the Dynamic World @ CVPR 2025.* [\[pdf\]](#)
- [S.1] M. M. Zhang, H. Kumawat, and S. Mukhopadhyay. **DFDNet: Directional Feature Diffusion for Efficient Fully-Sparse LiDAR Object Detection**. 2024. *Under review.* [\[pdf\]](#)
- [P.1] M. M. Zhang. **spkan: Sparse Convolutions with Kolmogorov-Arnold Networks**, 2024. *In preparation.* [\[github\]](#)

## EXPERIENCE

- **Trustworthy Robotics Lab** Jul 2025 - Current  
*Graduate Research Assistant - Advisor: Prof. Glen Chou* Atlanta, USA
  - Projects: 3D perception (LiDAR), Foundation model reliability (VLA, VLM, Vid-LLM)
- **Gigascale Reliable Energy-Efficient Nanosystem Lab** Aug 2023 - Jul 2025  
*Graduate Research Assistant - Advisor: Prof. Saibal Mukhopadhyay* Atlanta, USA
  - Projects: Efficient perception
- **Knight Lab** Aug 2021 - May 2023  
*Undergraduate Research Assistant - Advisor: Prof. Robert Knight* Berkeley, USA
  - Projects: LLM interpretability

## HONORS AND AWARDS

- **Lambda Labs Research Grant** Jul 2025  
*Compute funding for research on active uncertainty mitigation in autonomous driving.*
- **UC Berkeley Rose Hills Fellowship** May 2022  
*Merit-based fellowship for independent summer research funding. One of 45 recipients selected university-wide.*
- **Georgia Tech SURE Fellowship** May 2021  
*Merit-based summer research internship. One of 50 recipients selected nationally.*

## SERVICE AND TEACHING

- **Teaching:** Graduate Teaching Assistant, AE 2610 Intro Experimental Methods in Aerospace, Fall 2025
- **Program Committee:** CoRL ('25)
- **Project ENGAGES**, one-on-one research mentorship with high school student from Atlanta area. 2025-2026
- **Computer Science Mentors**, undergraduate tutor for CS61B: Data Structures 2020-2022

## SKILLS

- **Programming:** Python (PyTorch, Tensorflow, Scikit-learn etc.), C++, CUDA, LaTeX, Java, Javascript, C, RISC-V
- **Development:** Linux, bash, Git, SLURM, HPC